

ΘΕΜΑ Α

- A1) δ A2) γ A3) δ A4) B A5) Σ, Λ, Λ, Σ, Σ

ΘΕΜΑ Β

B1)  $\Delta x = 2t^2 (s_1)$  Από σχέση:  $\frac{1}{2}a = 2 \Rightarrow a = 4 \text{ m/s}^2$   
 $\Delta x = \frac{1}{2}at^2$

$\sum F = ma \Rightarrow F_1 - F_2 = ma \Rightarrow 10 - F_2 = 2 \cdot 4 \Rightarrow F_2 = 2 \text{ N}$   $\Sigma \Omega \Sigma T_0 \tau_0 (\alpha)$

B2)  $d_1 = \frac{v_1^2}{2a} = \frac{\left(\frac{v_2}{2}\right)^2}{2a} = \frac{1}{4} \frac{v_2^2}{2a} = \frac{1}{4} d_2 \Rightarrow d_2 = 4d_1$   $\Sigma \Omega \Sigma T_0 \tau_0 (\delta)$

B3) 0-10s:  $\Delta x_1 = E_1 = \frac{10 \cdot 10}{2} \text{ m} = 50 \text{ m}$ ,  $s_1 = |\Delta x_1| = 50 \text{ m}$

10s-20s:  $\Delta x_2 = E_2 = \frac{10 \cdot 10}{2} \text{ m} = 50 \text{ m}$ ,  $s_2 = |\Delta x_2| = 50 \text{ m}$

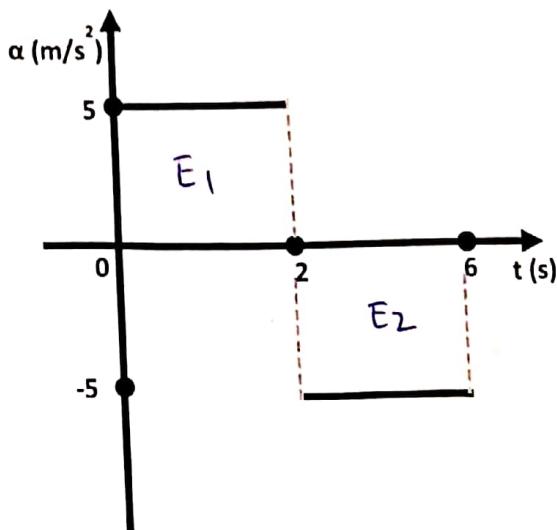
20s-25s:  $\Delta x_3 = \frac{5 \cdot (-5)}{2} \text{ m} = -\frac{25}{2} \text{ m}$ ,  $s_3 = |\Delta x_3| = \frac{25}{2} \text{ m}$

25s-30s:  $\Delta x_4 = \frac{5 \cdot (-5)}{2} \text{ m} = -\frac{25}{2} \text{ m}$ ,  $s_4 = |\Delta x_4| = \frac{25}{2} \text{ m}$

Άρτι  $S = s_1 + s_2 + s_3 + s_4 = 50 \text{ m} + 50 \text{ m} + \frac{25}{2} \text{ m} + \frac{25}{2} \text{ m} \Rightarrow S = 125 \text{ m}$

$\Delta x_{\text{tot}} = \Delta x_1 + \Delta x_2 + \Delta x_3 + \Delta x_4 = 50 \text{ m} + 50 \text{ m} + \left(-\frac{25}{2} \text{ m}\right) + \left(-\frac{25}{2} \text{ m}\right) \Rightarrow \Delta x_{\text{tot}} = 75 \text{ m}$   $\Sigma \Omega \Sigma T_0 \tau_0 (\delta)$

B4. Η επιτάχυνση ενός κινητού, που κινείται ευθύγραμμα κατά μήκος του άξονα  $x$ , μεταβάλλεται σε διάφορη με τον χρόνο, σύμφωνα με το παρακάτω διάγραμμα. Την χρονική στιγμή  $t_0 = 0s$  η τιμή της ταχύτητας του κινητού είναι  $v_0 = 2 \frac{m}{s}$ .



Την χρονική στιγμή  $t = 6s$  το κινητό:

- a. θα έχει σταματήσει να κινείται
- β. το μέτρο της ταχύτητας του θα αυξάνεται
- γ. το μέτρο της ταχύτητας του θα μειώνεται

$$E_1 = \Delta v_1 = 5 \cdot 2 \Rightarrow \Delta v_1 = 10 \text{ m/s}$$

$$\Delta v_1 = v_1 - v_0 \Rightarrow v_1 = \Delta v_1 + v_0 = 10 + 2 \Rightarrow v_1 = 12 \text{ m/s}$$

$$E_2 = \Delta v_2 = 4 \cdot (-5) \Rightarrow \Delta v_2 = -20 \text{ m/s}$$

$$\Delta v_2 = v_2 - v_1 \Rightarrow v_2 = \Delta v_2 + v_1 = -20 + 12 \Rightarrow v_2 = -8 \text{ m/s}$$

$\Sigma \underline{\underline{v}} = \underline{\underline{v}}$  (B)

# ΘΕΜΑ Γ

1<sup>η</sup> κίρκων:  $\Delta x_1 = \frac{1}{2} \alpha_1 \Delta t_1^2 = \frac{1}{2} \cdot 3 \cdot 10^2 \Rightarrow \Delta x_1 = 150m$ ,  $s_1 = 150m$

$A \rightarrow B$   $\Delta x_1 = x_1 - x_0 \Rightarrow 150m = x_1 - 5m \Rightarrow x_1 = 155m$

$U_1 = \alpha_1 \Delta t_1 = 3 \cdot 10 \Rightarrow U_1 = 30m/s$

2<sup>η</sup> κίρκων  $B \rightarrow C$   $U_2 = U_1 = 30m/s = 62\%$ .

$\Delta x_2 = U_2 \Delta t_2 = 30 \cdot 6 \Rightarrow \Delta x_2 = 180m$ ,  $s_2 = 180m$

$\Delta x_2 = x_2 - x_1 \Rightarrow 180m = x_2 - 155m \Rightarrow x_2 = 335m$

3<sup>η</sup> κίρκων  $C \rightarrow D$   $\Delta x_3 = \frac{U_{3\text{ef}}^2}{2\alpha_3} = \frac{30^2}{2 \cdot 5} \Rightarrow \Delta x_3 = 90m$ ,  $s_3 = 90m$

$\Delta t_3 = \frac{U_{3\text{ef}}}{\alpha_3} = \frac{30}{5} \Rightarrow \Delta t_3 = 6s$

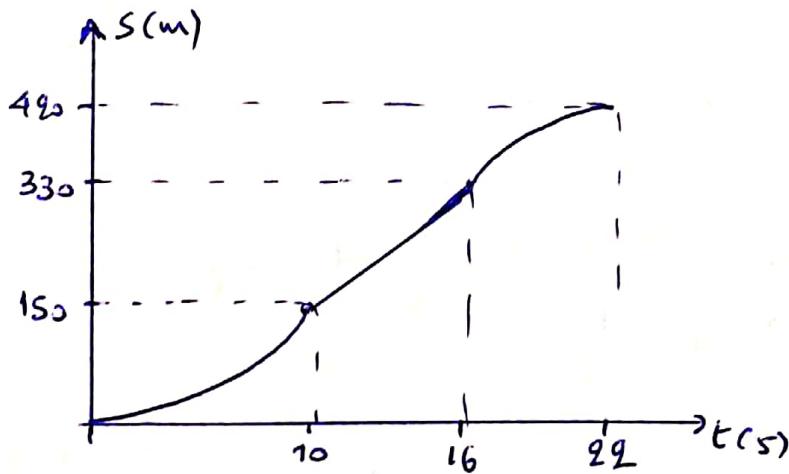
Γ1)  $\Delta x_3 = x_3 - x_2 \Rightarrow 90m = x_3 - 335m \Rightarrow x_3 = 425m$

Γ1<sup>η</sup> Τις τρεις πρώτες κυρίσεις ( $A \rightarrow D$ ):  $s_{\text{tot}} = s_1 + s_2 + s_3 \Rightarrow s_{\text{tot}} = 420m$

$t_{\text{tot}} = \Delta t_1 + \Delta t_2 + \Delta t_3 = 22s$

$$U_{\text{av}} = \frac{s_{\text{tot}}}{t_{\text{tot}}} = \frac{420m}{22s} = 19.1m/s$$

Γ2)



Γ3)  $t_1 = 8s$   $x'_1 = x_0 + \frac{1}{2} \alpha_1 \Delta t^2 = 5 + \frac{1}{2} \cdot 3 \cdot (8-0)^2 = 5 + \frac{1}{2} \cdot 3 \cdot 64 \Rightarrow$

$x'_1 = 101m$   $U_1 = \alpha_1 \Delta t = 3 \cdot 8 \Rightarrow U_1 = 24m/s$

Γ4<sup>η</sup>  $t_2 = 22s$ :

Αρχ.  $22s \in$  ως  $2s$ :  $|\Delta x_4| = \frac{1}{2} \alpha_4 \Delta t^2 = \frac{1}{2} \cdot 2 \cdot (22-20)^2 = 9m$

η  $\Delta x_4 = -9m$

$$x'_4 = x_3 + \Delta x_4 = 425m + (-9m) \Rightarrow x'_4 = 416m$$

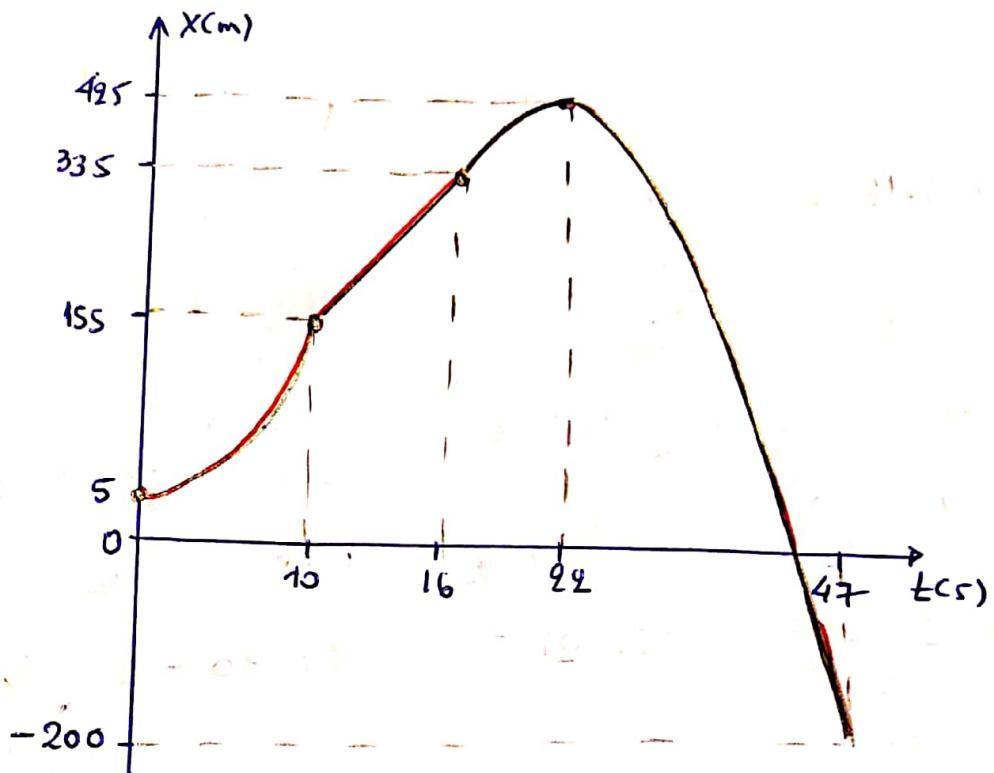
$$|U_4| = |\alpha_4| \Delta t = 2 \cdot (22-20) \Rightarrow |U_4| = 6m/s \quad \text{η } U_4 = -6m/s$$

4) Añ TN deon (A) pos en deon (E) par epícular  
 $d = 905m$  apreciando deon (A) =  $S_4 = 49m + 905m \Rightarrow S_4 = 954m$   
 $S_4 = \frac{1}{2} |a_4| \Delta t_4^2 = \frac{1}{2} \cdot 2 \Delta t_4^2 \Rightarrow 954 = \Delta t_4^2 \Rightarrow \Delta t_4 = \sqrt{954} \Rightarrow$   
 $\Rightarrow \Delta t_4 = 31\text{sec.}$  con  $|U_4| = |a_4| \Delta t_4 = 2 \cdot 31 = 62\text{m/s}$  y  $U_4 = -62\text{m/s}$

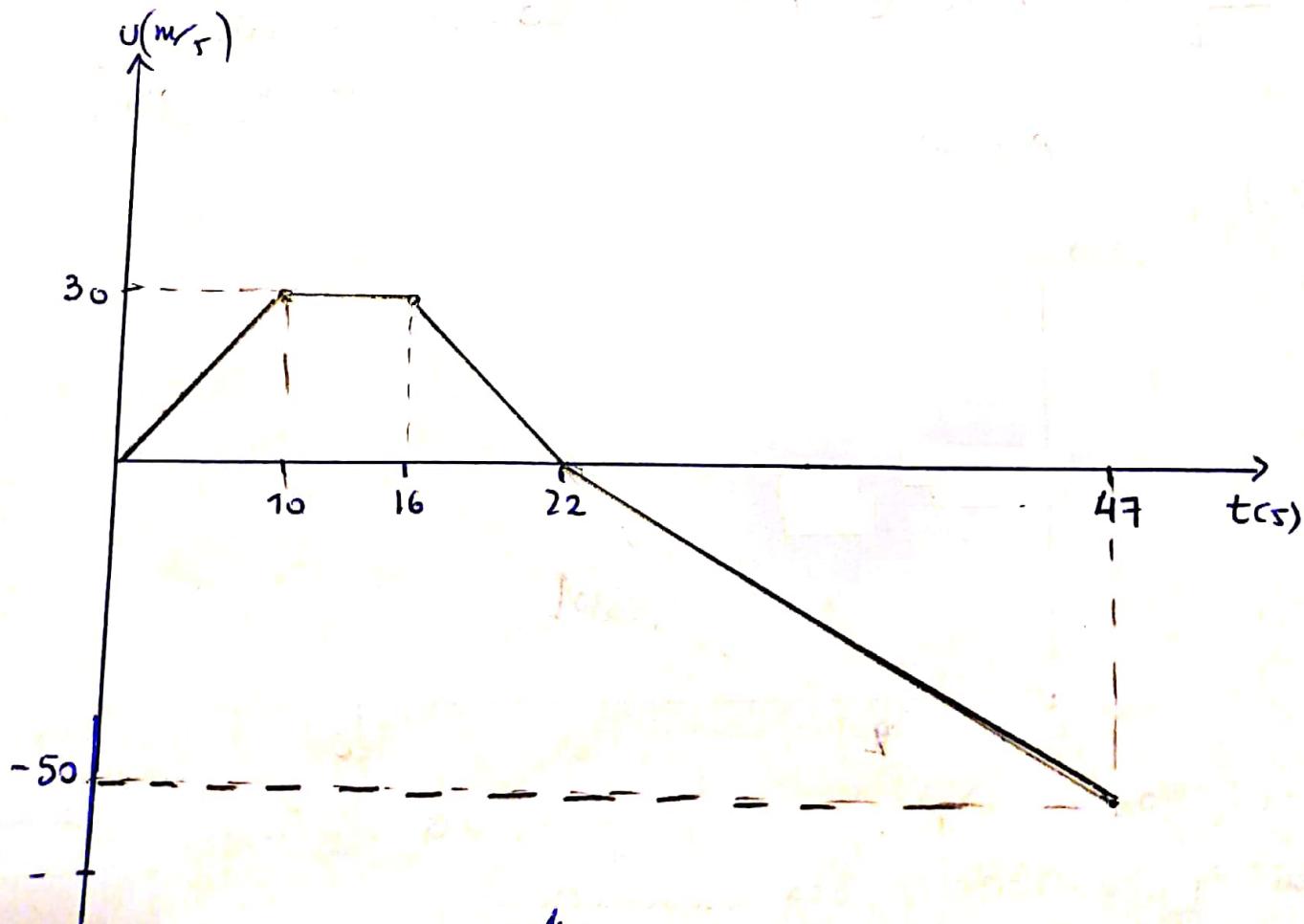
TN deon (E):  $x_4 = x_3 + \Delta x_4 = 49\text{m} + (-62\text{m}) \Rightarrow x_4 = -15\text{m}$ .

a)

| $t(\text{s})$ | $x(\text{m})$ |
|---------------|---------------|
| 0             | 5             |
| 10            | 155           |
| 16            | 335           |
| 22            | 495           |
| 47            | -200          |



b)



ΘΕΜΑ Δ

$$\Delta 1) \quad \alpha_1 = \frac{\Delta v}{\Delta t} = \frac{60-0}{15-0} \text{ m/s}^2 \Rightarrow \boxed{\alpha_1 = 4 \text{ m/s}^2}$$

$$v_1 = \alpha_1 t_1 \Rightarrow 60 = 4 \cdot t_1 \Rightarrow \boxed{t_1 = 15 \text{ s}}$$

$$\Delta 2) \quad s_1 = \frac{1}{2} \alpha_1 \Delta t^2 = \frac{1}{2} \cdot 4 \cdot 15^2 \Rightarrow s_1 = 450 \text{ m}$$

$$s_2 = v_2 \cdot \Delta t = 60 \cdot 15 \Rightarrow s_2 = 900 \text{ m}$$

$$d = s_2 - s_1 \Rightarrow \boxed{d = 450 \text{ m}}$$

$$* \quad t_1 + t = 15 \text{ s}$$

$$s_2 = v_2 \cdot t = 60 \cdot 15 = 900 \text{ m}$$

$$s_1 = \frac{1}{2} \alpha_1 t^2 = \frac{1}{2} \cdot 4 \cdot 15^2 = 450 \text{ m}$$

Ergen  $s_2 > s_1$  το  $s_2$

αρχικής θέσης των  $s_1$ .

H συγχρόνως δείχνει ότι  $t_2 > 15 \text{ sec}$ .

\*  $t_1 < t_2 < 15 \text{ s}$  λόγω της:

$$\Rightarrow s_1 = s_2 \Rightarrow E_1 = E_2 \Rightarrow E_{\text{ΤΡΑΠΕΖΙΚΗ}} = E_{\text{Επαγγελματική}} \Rightarrow (B+B)v = 40t_2 \Rightarrow$$

$$\Rightarrow [t_2 + (t_2 - 15)] \cdot 60 = 40t_2 \Rightarrow (2t_2 - 15)30 = 40t_2 \Rightarrow \frac{2t_2 - 15}{2} = \frac{40t_2}{2} \Rightarrow$$

$$\Rightarrow 60t_2 - 450 = 40t_2 \Rightarrow 20t_2 = 450 \Rightarrow \boxed{t_2 = 22,5 \text{ s}}$$

$$\Delta 4) \quad s_1 = s_2 \Rightarrow \frac{1}{2} \alpha_1 (t-q)^2 = \frac{1}{2} \alpha_2 t^2 \Rightarrow \frac{\alpha_1}{\alpha_2} = \frac{t^2}{(t-q)^2} \Rightarrow \frac{2,5}{1,6} = \left(\frac{t}{t-q}\right)^2 \Rightarrow$$

$$\Rightarrow \left(\frac{t}{t-q}\right)^2 = \frac{25}{16} \Rightarrow \frac{t}{t-q} = \pm \sqrt{\frac{25}{16}} \Rightarrow \frac{t}{t-q} = \pm \frac{5}{4}$$

$$\bullet \quad \frac{t}{t-q} = -\frac{5}{4} \Rightarrow 5(t-q) = -4t \Rightarrow 5t - 5q = -4t \Rightarrow 9t = 5q \Rightarrow t = \frac{5q}{9} \text{ s} \quad \text{Απόπτετο}$$

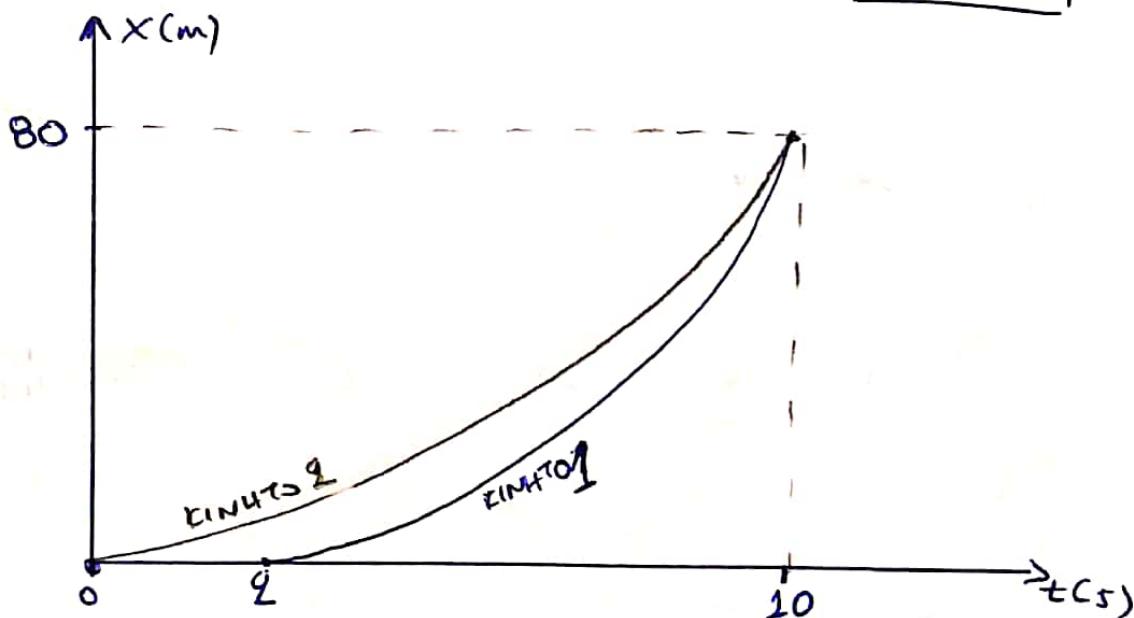
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(\* Δεύτερες ειφές για  $t > 15 \text{ s}$ )

$$\bullet \quad \frac{t}{t-q} = +\frac{5}{4} \Rightarrow 5(t-q) = +4t \Rightarrow 5t - 5q = 4t \Rightarrow t = 5q \text{ s} \quad \text{Δεκτό}$$

$$\text{Άρχικά } t_q = 10 \text{ s}$$

Δ5)



$$t_1 + t = t_q = 10 \text{ s} : \quad x_q = \frac{1}{2} \alpha_2 t_q^2 = \frac{1}{2} \cdot 1,6 \cdot 10^2 = 80 \text{ m}$$

και  $x_1 = x_2 = 80 \text{ m}$ , διανομής.